



Development of the RAPTOR suite of codes towards real-time reconstruction of JET discharges

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This work has been carried out within the framework of the EUROfusion Consortium and has received funding from the Euratom research and training programme 2014-2018 and 2019-2020 under grant agreement No 633053. The views and opinions expressed herein do not necessarily reflect those of the European Commission.

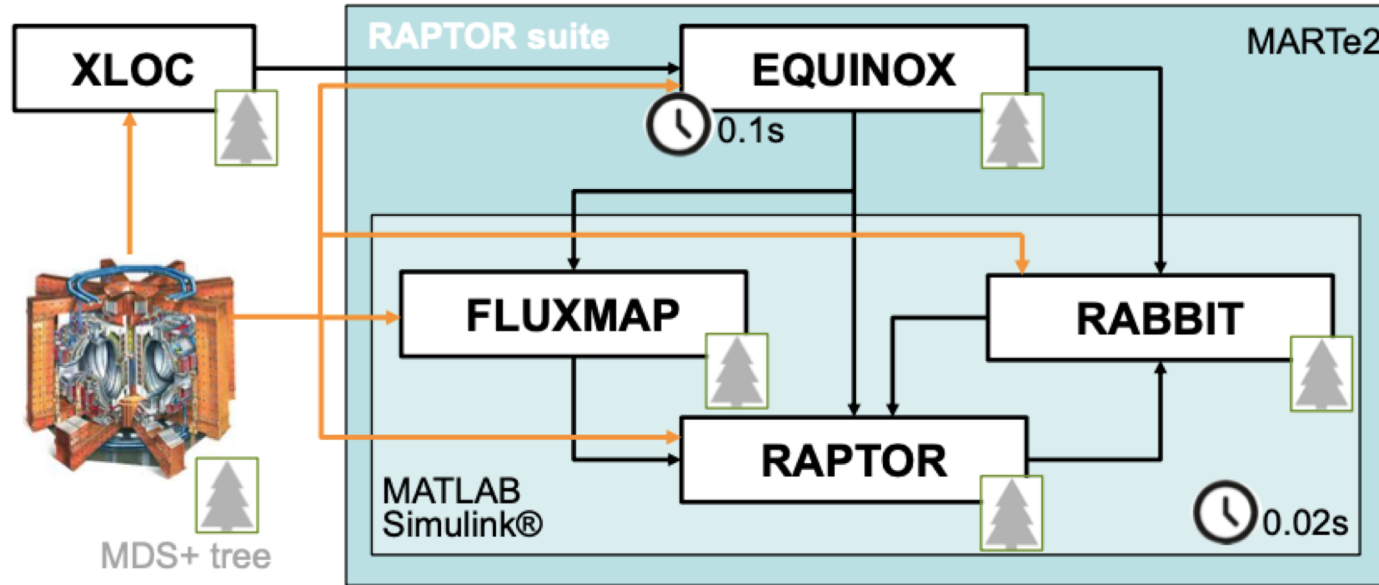


- ❑ A well-coordinated control of plasma profiles and key integrated quantities is crucial for:
 - ✓ future reactors: high performance and reliability
 - ✓ present experiments: limited pulse budget (T, neutrons)
- ❑ The RAPTOR suite integrates Real-Time (RT) control-oriented codes (equilibrium, energy transport, H/CD) with diagnostic measurements.

A bifold tool: in Matlab/Simulink[®]: fast offline modelling
 in MARTe2: real-time integrated control

- ❑ Available at TCV, AUG, RFX-mod and here developed for JET

The RAPTOR suite for control-oriented modelling



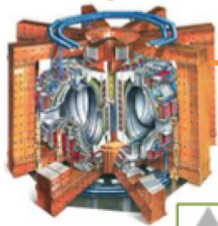
The RAPTOR suite for control-oriented modelling



Magnetic boundary



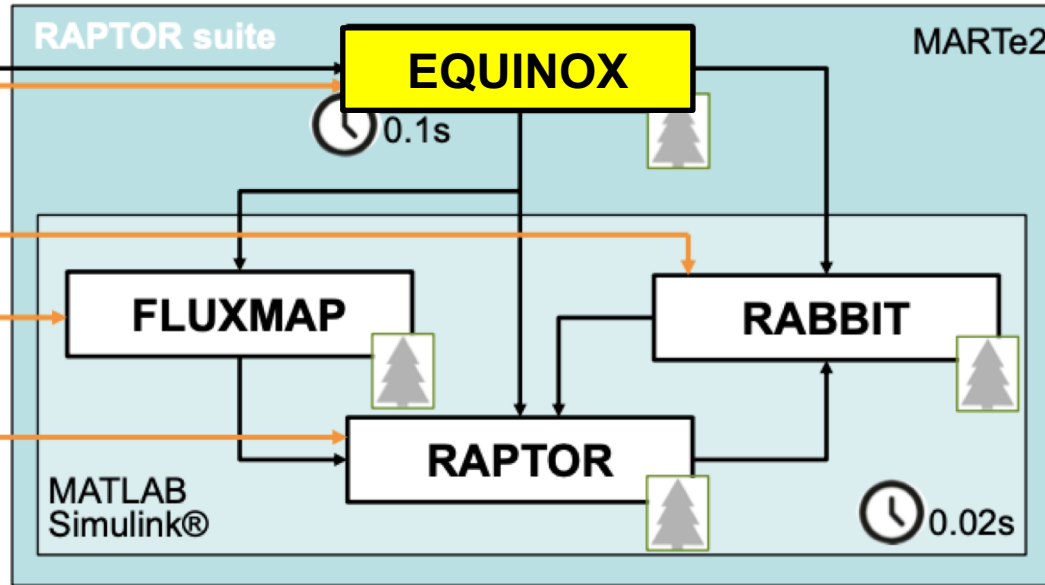
XLOC



MDS+ tree

Equilibrium reconstruction

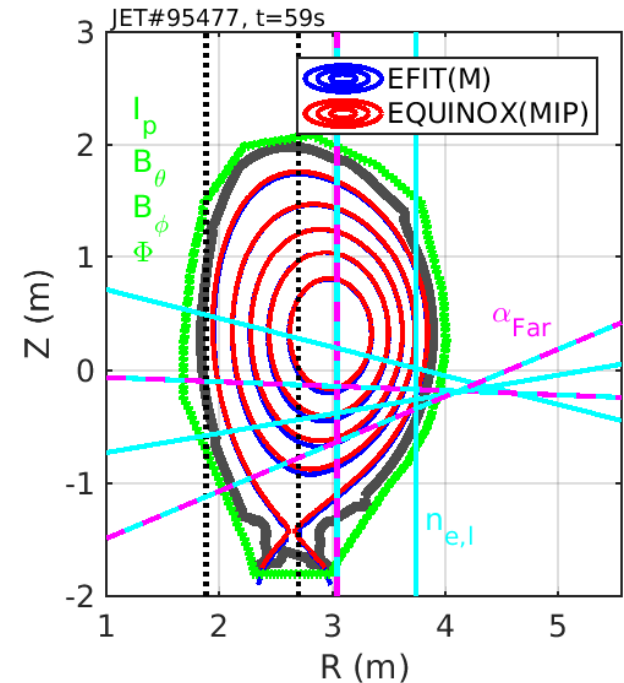
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The upgraded EQUINOX code



- The equilibrium reconstruction is constrained with magnetic, polarimetric and interferometric data [1]:
 - Improved **magnetic boundary** reconstruction from the XLOC code [2] using 216pts (67pts in [3]).
 - 3 **Faraday angle** and 6 **line integrated density** measurements, which are also inverted to provide an estimate of the plasma density profile.
- Surface and volume integrated quantities are evaluated and deployed in real-time.



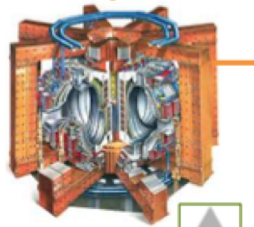
The RAPTOR suite for control-oriented modelling



Magnetic boundary



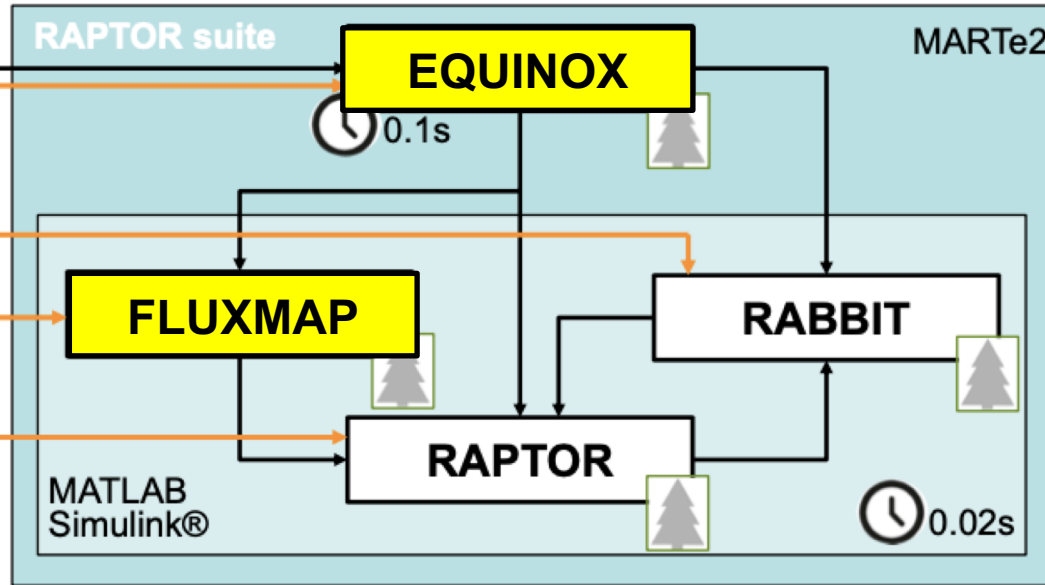
XLOC



MDS+ tree

Equilibrium reconstruction

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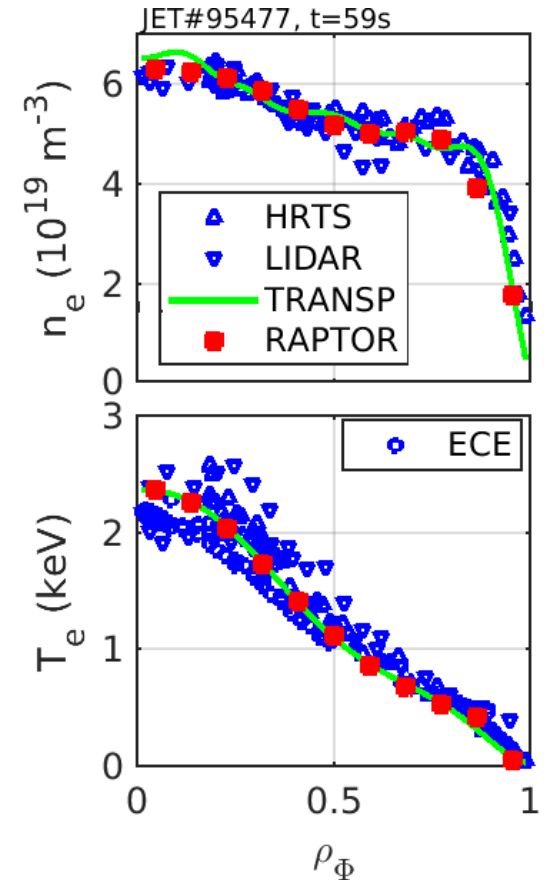
Re-mapper R to ρ



The brand-new FLUXMAP tool



- To re-map in RT the diagnostic measurements from the geometrical (m) to the poloidal and toroidal (ρ_Φ) normalized magnetic flux coordinates.
 - The RT temperature profile (T_e) is evaluated by radially locating the Electron Cyclotron Emission (ECE) resonances
 - Offline T_e and density (n_e) profiles also from the High Resolution Thomson Scattering (HRTS) and the Light Detection And Ranging (LIDAR) diagnostics



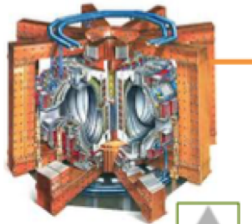
The RAPTOR suite for control-oriented modelling



Magnetic boundary



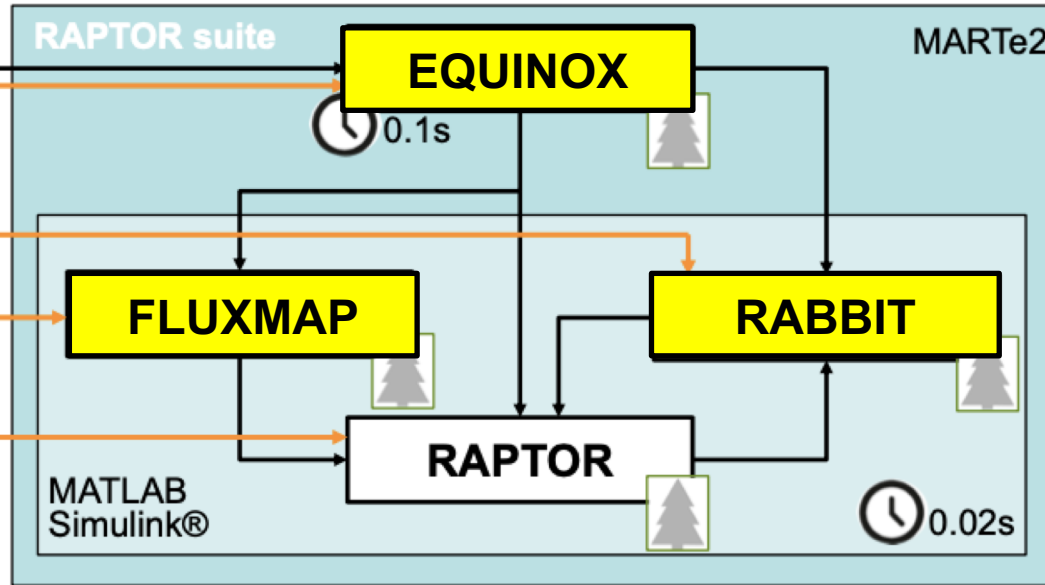
XLOC



MDS+ tree

Equilibrium reconstruction

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NBI

IPP Max Planck Institute for Plasma Physics

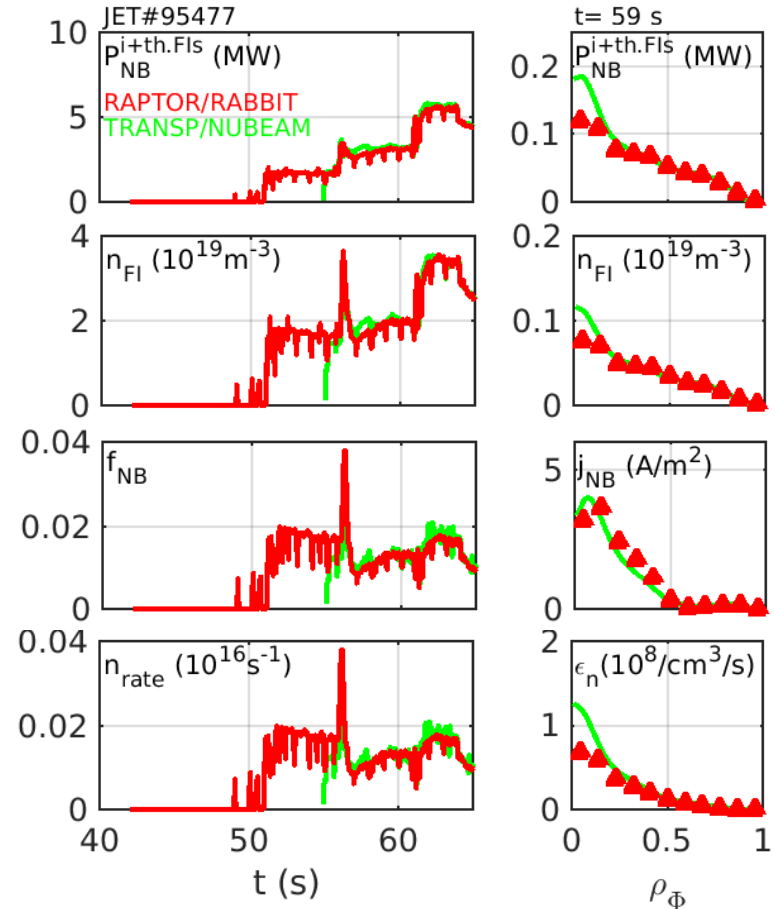
Re-mapper R to ρ



The RABBIT code



- ❑ It evaluates the NBH/CD, FI distribution [8] and the neutron emission [9] in real-time.
- ❑ It has been successfully benchmarked against NUBEAM [8].
- ❑ It models the 2 JET banks of 8 PINIs each using the kinetic profiles from RAPTOR observer and the EQUINOX equilibria.



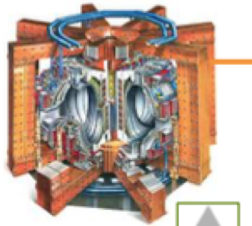
The RAPTOR suite for control-oriented modelling



Magnetic boundary



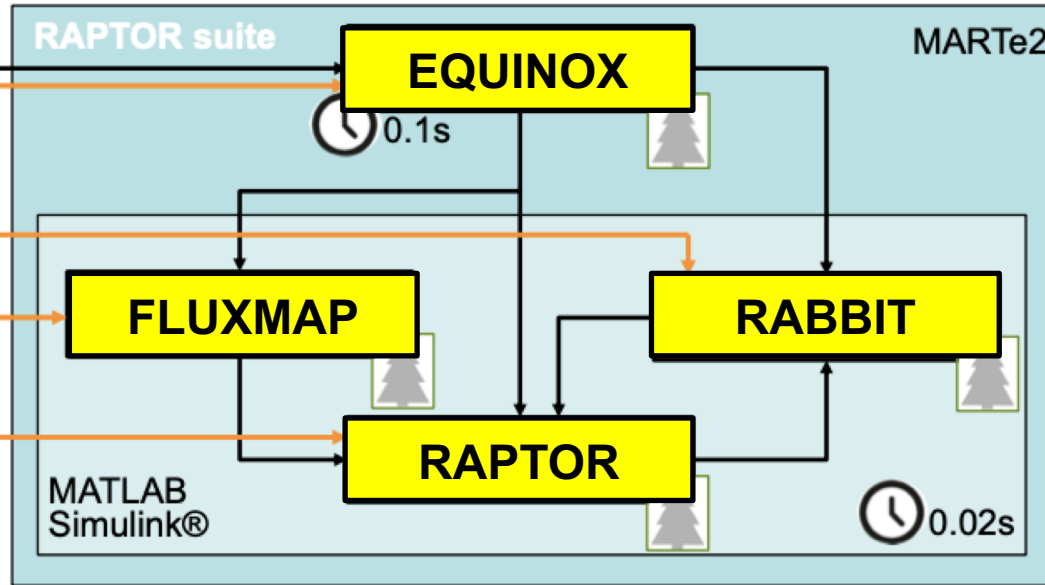
XLOC



MDS+ tree

Equilibrium reconstruction

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Re-mapper R to ρ

1D transport + state observer

EPFL



NBI



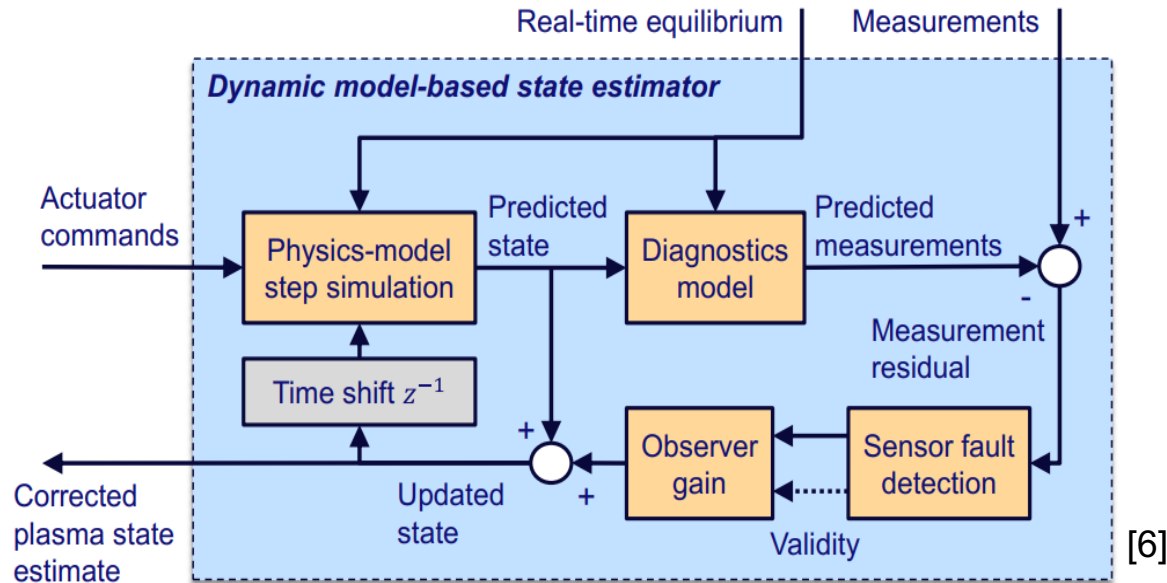
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The RAPTOR state-observer code



It combines the predictions of the 1D control-oriented transport code RAPTOR [4] with the available diagnostic data using an extended Kalman Filter [5].

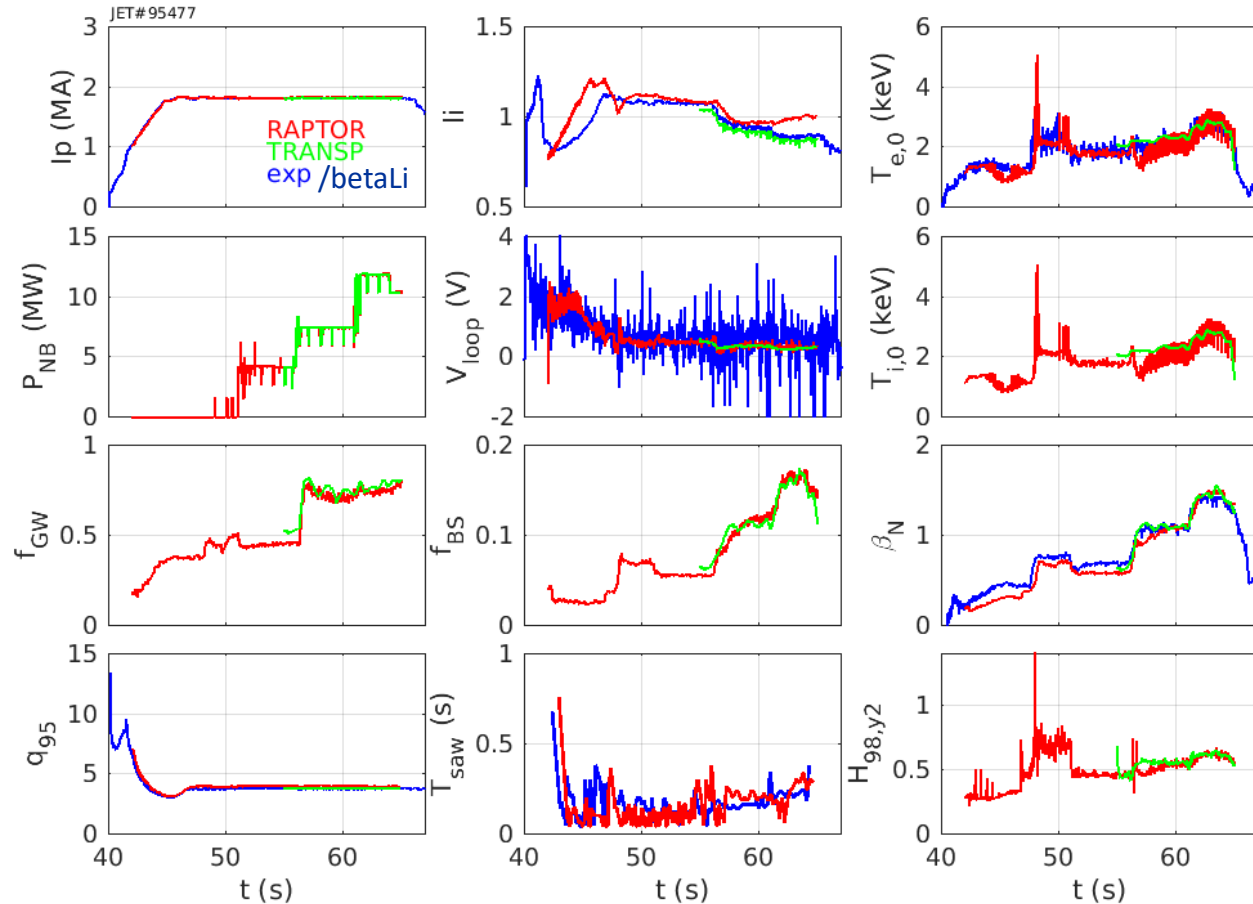




The version presented here **solves the coupled Ψ and T_e (observed quantity) equations**, assuming:

- Bohm-GyroBohm or empirical electron transport model
- $T_i \propto T_e$ (for NBI heated pulses $T_i \approx T_e$)
- Prescribed L/H-mode transition and $\nabla T_{e,ped}(I_p)$
- Density either from EQUINOX or from HRTS+LIDAR
- **Synthetic T_e diagnostic models for ECE and HRTS**
- ICRH/CD from a gaussian model, NBH/CD and FIs from RABBIT
- **Porcelli's sawtooth** model activated [7]
- **No Impurity transport** modelled

Some RT outputs from the RAPTOR suite



The RAPTOR suite for control-oriented modelling

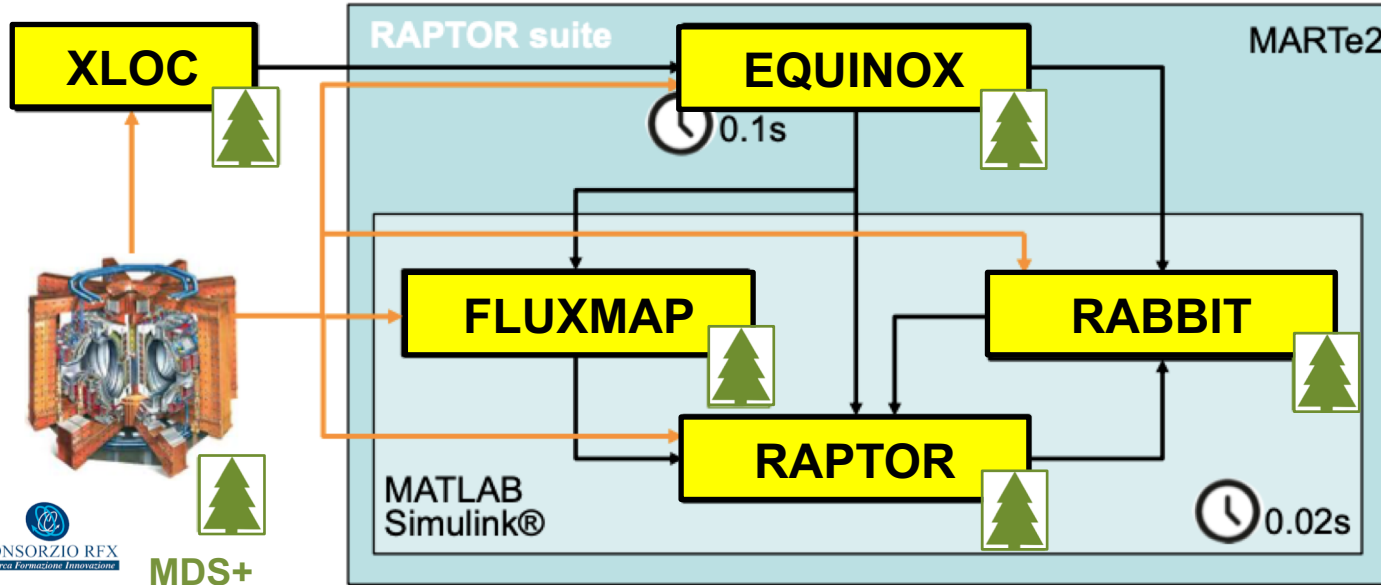


Magnetic boundary

Equilibrium reconstruction



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MDS+

Re-mapper R to ρ



1D transport + state observer

EPFL

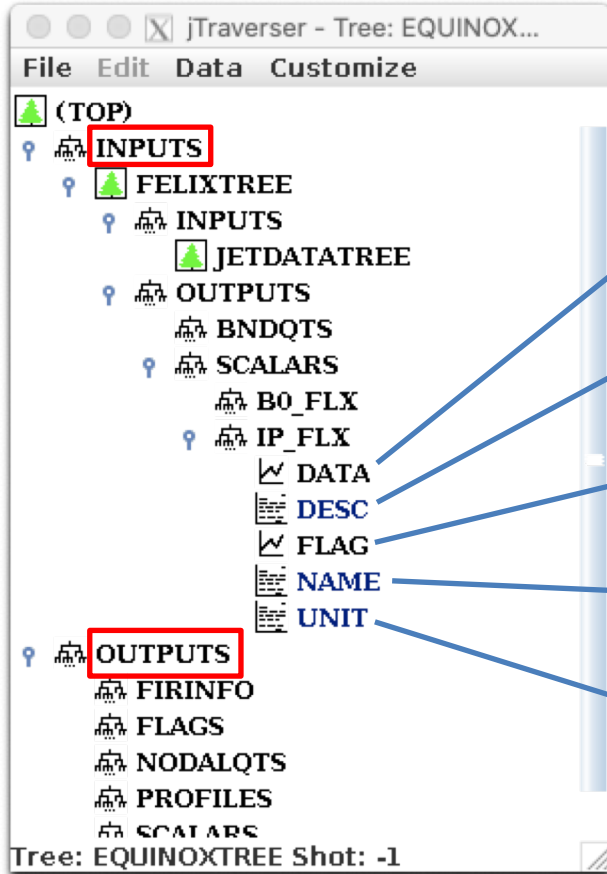


NBI



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The MDS+ software: jTraverser



Self-consistent set of I/O parameters and signals stored in linked subtrees

Data + embedded dimensionalities (t,R,..)

Concise description of the stored data

3-level «Sanity check» (good,unknow,invalid)

Tag shortcut

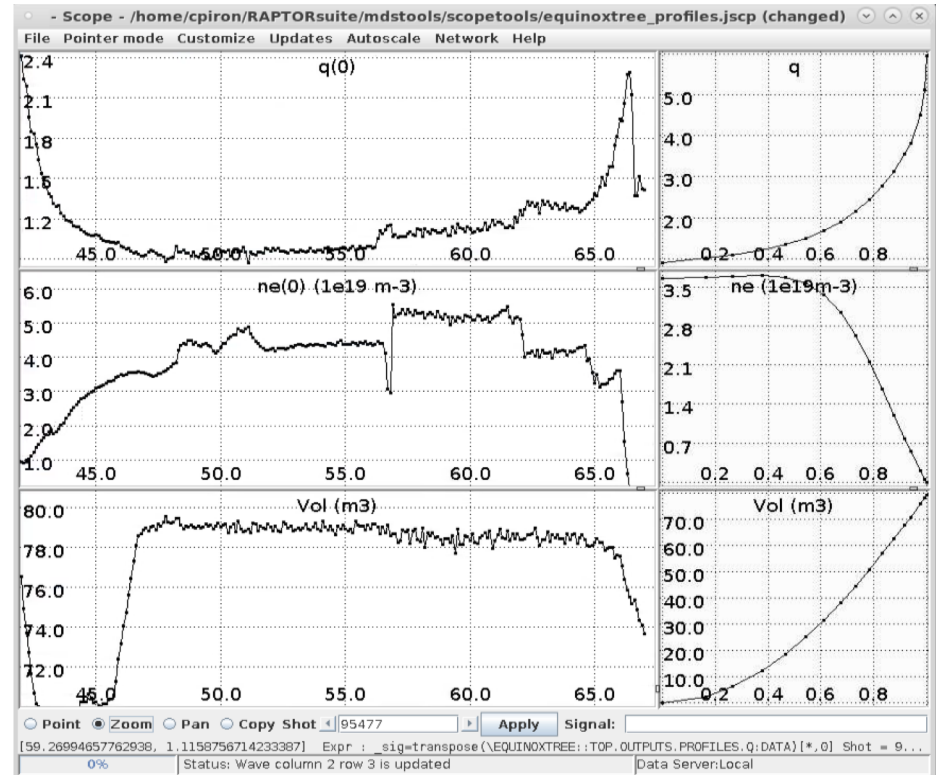
Physical units

The MDS+ software: jScope



Python script are available to:

- generate automatically the MDSplus [10] tree models and the jScope configurations on the the basis of [.CVS](#) or MARTe2 configuration files
- fill them with the pulse data

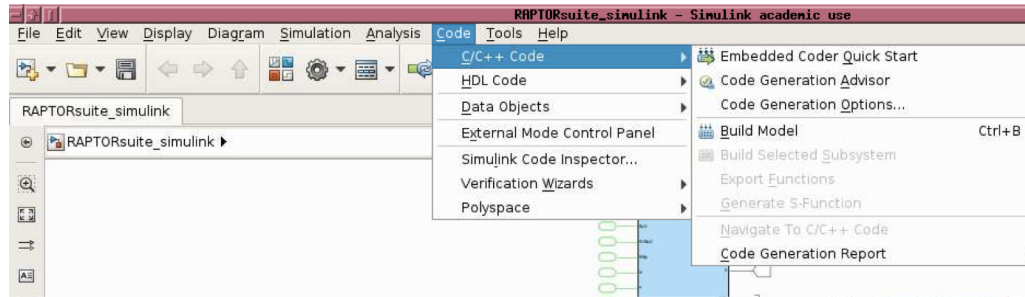


```
Node,SubNode,SubSubNode,Name,S/P,Dims,Units,Description
INPUTS,FELIXTREE,,,,,> felixtree > jetdatatree
OUTPUTS,FIRINFO,,NECALC,S,"(*,8)",m-2,Calculated Ne (all lines)
```

Integration in the MARTe2 framework



- ❑ The MATLAB/Simulink® model of the RAPTOR suite is automatically converted using the Embedded Coder® toolbox



- ❑ A standardised, automatised and quality-compliant procedure to integrate the generated code in the MARTe2 framework [11] is being developed in collaboration with F4E, EPFL-SPC, Consorzio RFX and ENEA
- ❑ When executed in MARTe2, the output signals including those to monitor the real-time performance are streamed online

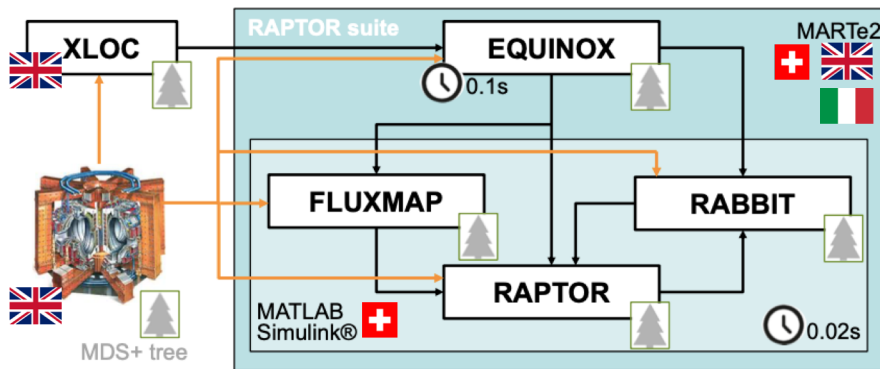


- ❑ The RAPTOR suite combines RT model-based reconstructions of the plasma state with the available diagnostic measurements.
- ❑ It is both implemented in MATLAB/Simulink® and it is being integrated in the C++ real-time MARTe2 framework → offline and real-time modelling
- ❑ MDS+ software to handle user interfaces
- ❑ The suite has been validated and compared with TRANSP simulations in NBI heated JET pulses.

On-going and future developments



- ❑ Deployment of the suite in a dedicated local pc in the JET control room



- ❑ Extension of the modeling database to high performance plasmas (high current, high ICRH+NBI power, impurity)
- ❑ Integration of the real-time METIS-like ICRH model (collaboration with IPP Prague)
- ❑ H-mode transition model
- ❑ EQUINOX and EFIT extensive benchmark on high pressure pulses



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- [2] F. Sartori, A. Cenedese, F. Milani, Fusion Engineering and Design 66-68 (2003) 735-739.
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- [4] F. Felici et al., Plasma Physics and Controlled Fusion 54-2 (2012) 025002.
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- [6] Felici, F. et al. 2016 in 26th IAEA Fusion Energy Conference, Kyoto, Japan EX/P8–33
- [7] C. Piron et al., Fusion Engineering and Design 123 (2017) 616-619.
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- [10] J. Stillerman, T. W. Fredian, Fusion Engineering and Design 43 3-4 (1999) 301-308.
- [11] <https://vcis.f4e.europa.eu/marte2-docs/master/html/index.html>